Taming Dynamic Memory

An Introduction to Custom Allocators

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code::dive, November 7, 2018

About me

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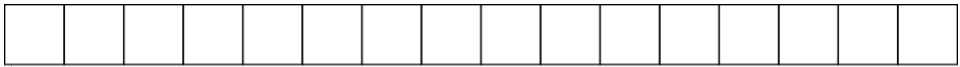
- Currently working as a Software Architect for BMW 

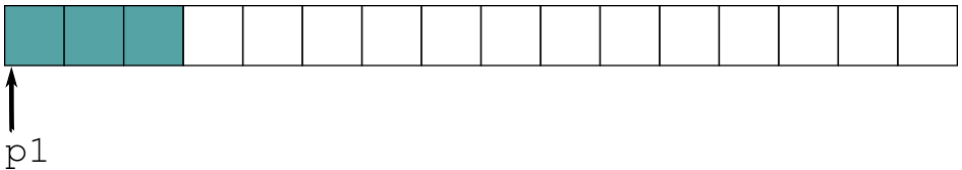
Overview

- What's wrong with global `new` and `delete`?
- Local allocators
- Alternative allocation strategies
- Allocator support in C++

General purpose allocator

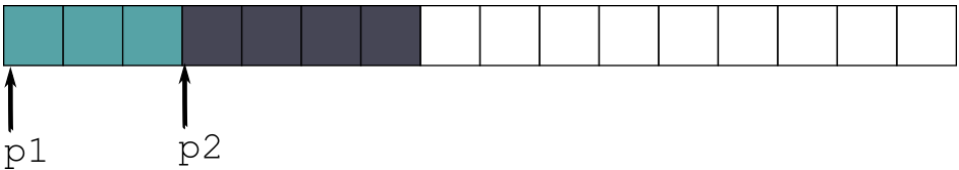


General purpose allocator



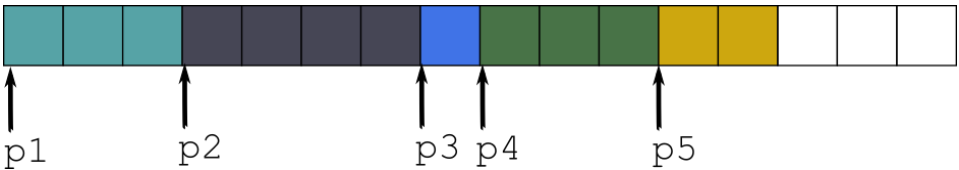

```
auto p1 = allocate(3);
```

General purpose allocator



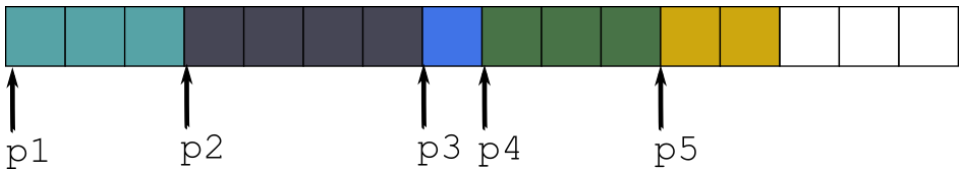

```
auto p1 = allocate(3);
auto p2 = allocate(4);
```

General purpose allocator

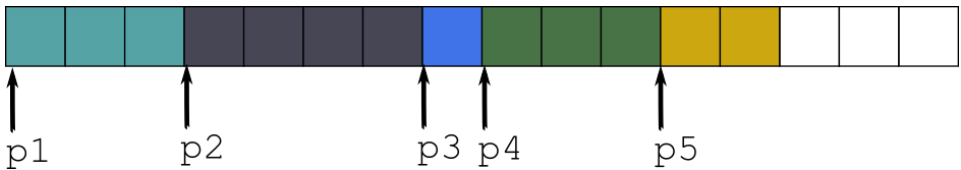



```
auto p1 = allocate(3);
auto p2 = allocate(4);
auto p3 = allocate(1);
auto p4 = allocate(3);
auto p5 = allocate(2);
```

General purpose allocator



General purpose allocator




```
deallocate(p2);
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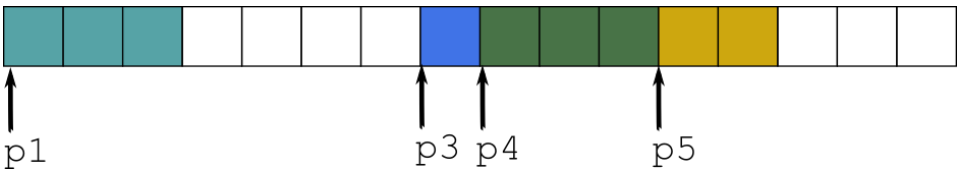
General purpose allocator

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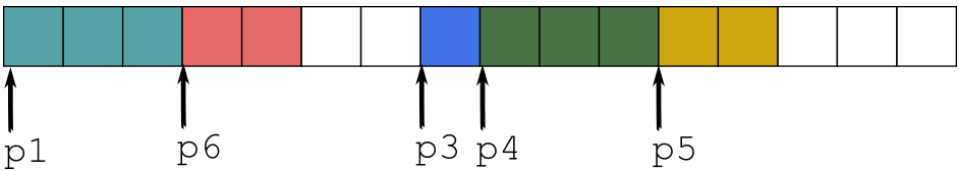
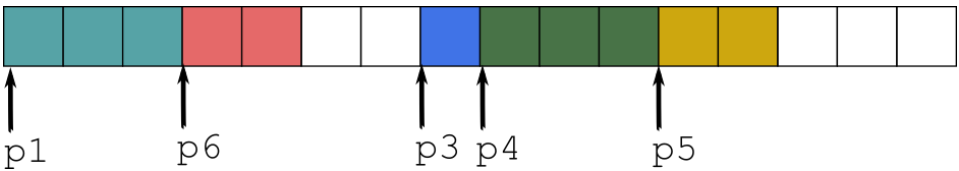
General purpose allocator



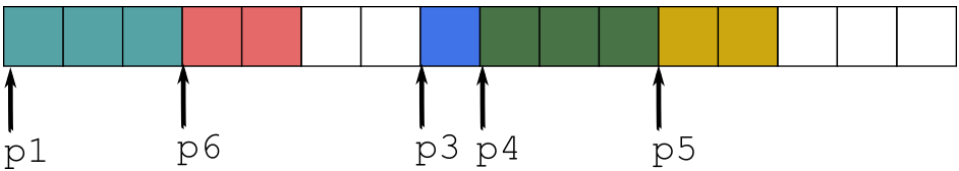

```
deallocate(p2);
auto p6 = allocate(2);
```

Fragmentation




```
auto p7 = allocate(4);
```

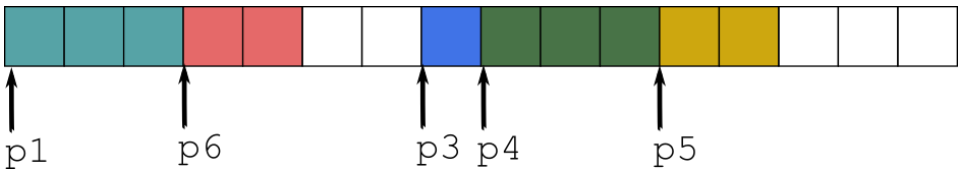
Fragmentation




```
auto p7 = allocate(4);
```

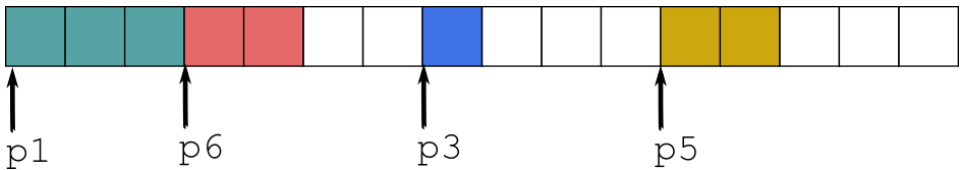
Runtime Error!

Coalescing



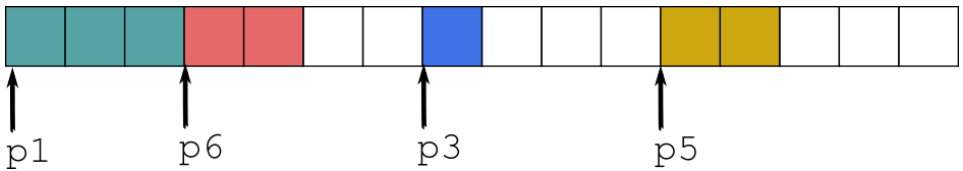

```
deallocate(p4);
```

Coalescing



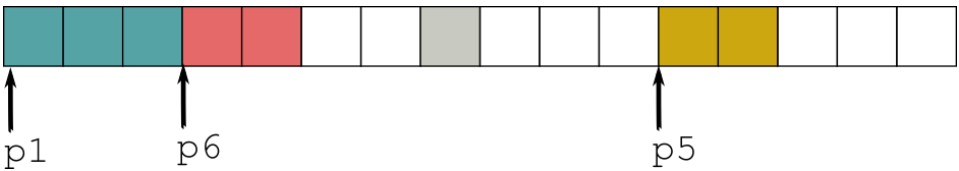

```
deallocate(p4);
```

Coalescing




```
deallocate(p4);
deallocate(p3);
```

Coalescing

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deallocate(p4);
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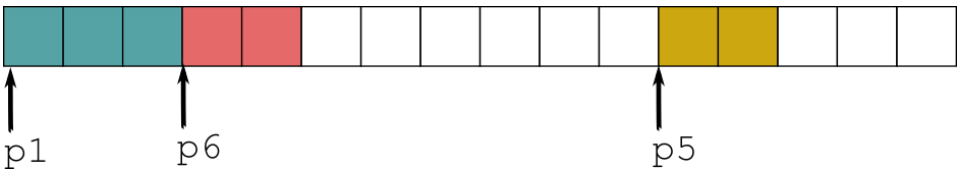
Coalescing




```
deallocate(p4);
deallocate(p3);
```

Problems with default allocator

- Complex runtime behavior
  - What is the maximum memory usage?
  - What is the worst-case execution time for an allocation or deallocation?
- Shared global state
  - Reasoning about allocator behavior requires global knowledge of the whole program
  - The singular resource global allocator is a potential bottleneck

It's not just about performance!

From Global to Local

```
auto p1 = allocate(42);
deallocate(p1);
```

From Global to Local

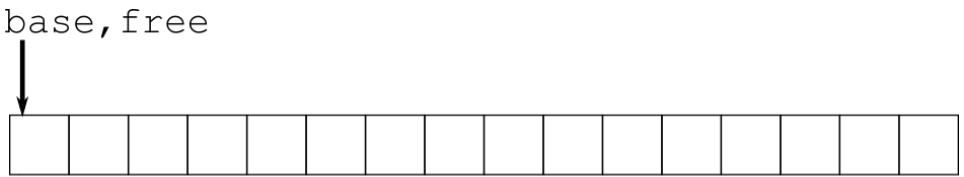
```
Allocator alloc;

auto p1 = alloc.allocate(42);
alloc.deallocate(p1);
```

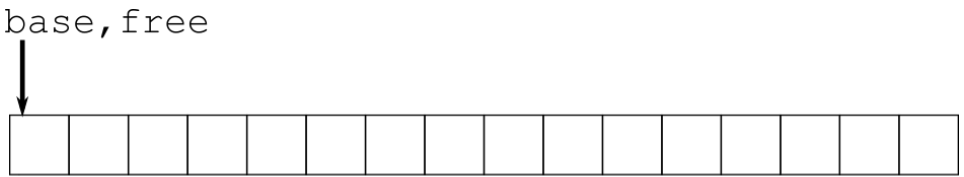
Problems with default allocator

- Complex runtime behavior
  - What is the maximum memory usage?
  - What is the worst-case execution time for an allocation or deallocation?
- Shared global state ✓

Monotonic Allocator

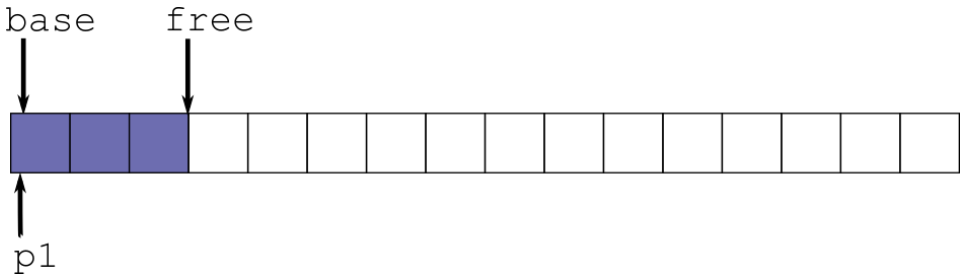


Monotonic Allocator




```
auto p1 = monot.allocate(3);
```

Monotonic Allocator

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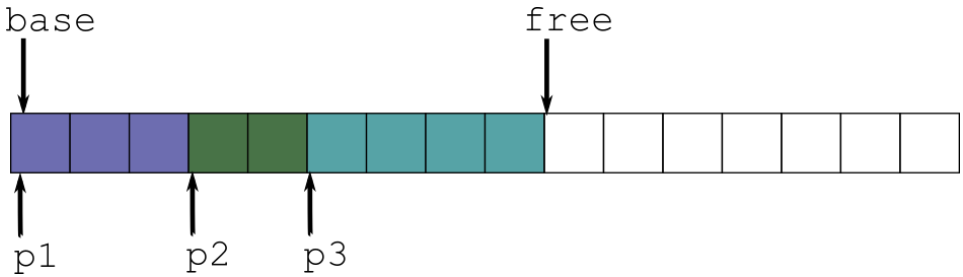
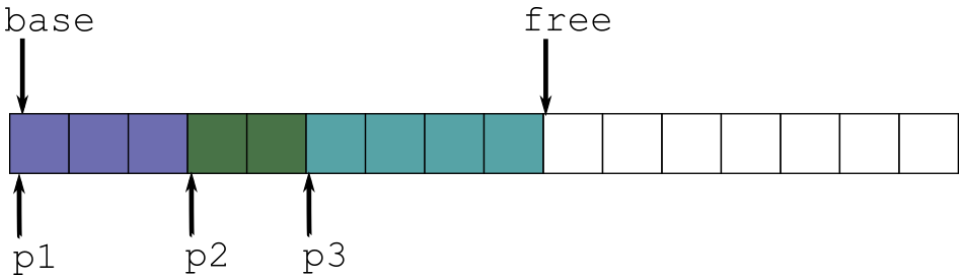
Monotonic Allocator



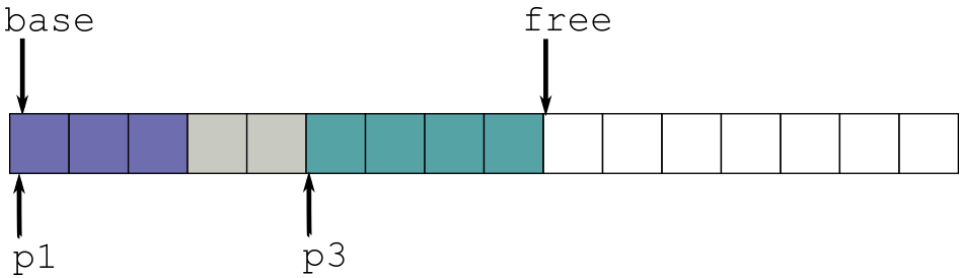

```
auto p1 = monot.allocate(3);
auto p2 = monot.allocate(2);
auto p3 = monot.allocate(4);
```

Monotonic Allocator




```
monot.deallocate(p2);
```

Monotonic Allocator

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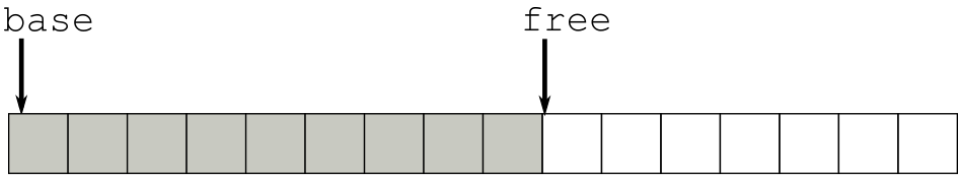
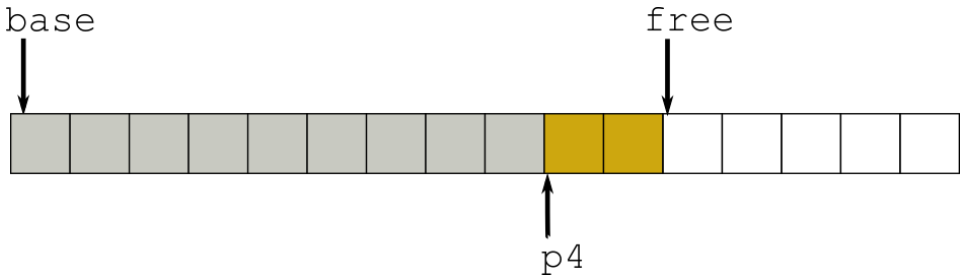
Monotonic Allocator




```
monot.deallocate(p2);
monot.deallocate(p1);
monot.deallocate(p3);
```

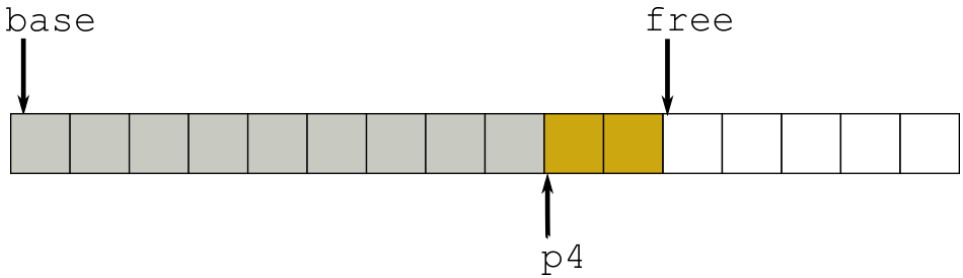
Monotonic Allocator




```
monot.deallocate(p2);
monot.deallocate(p1);
monot.deallocate(p3);

auto p4 = allocate(2);
```

Monotonic Allocator




```
monot.deallocate(p2);
monot.deallocate(p1);
monot.deallocate(p3);

auto p4 = allocate(2);
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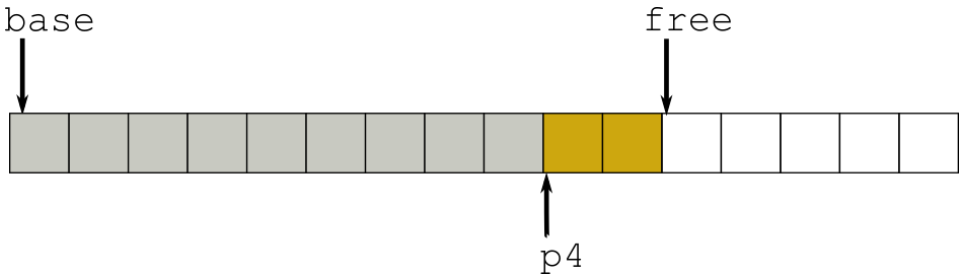
Monotonic Allocator - Reclamation




```
monot.deallocate(p4);
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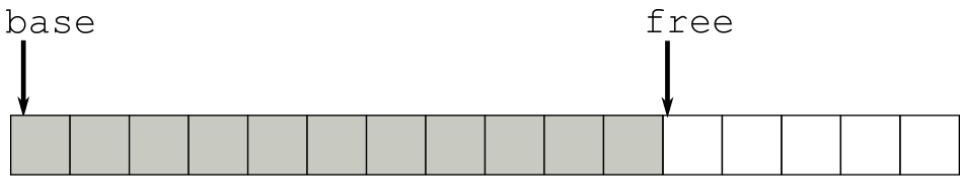


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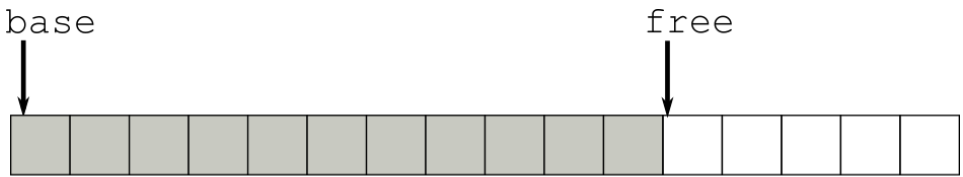
Monotonic Allocator - Reclamation




```
monot.deallocate(p4);
```

```
monot.release();
```

Monotonic Allocator - Reclamation


```
monot.deallocate(p4);

monot.release();
```

Monotonic Allocator

- Deterministic runtime cost
- Extremely efficient
- No fragmentation
- Easy to implement
- Trivial to make thread-safe

But:

- Memory can only be reclaimed all at once

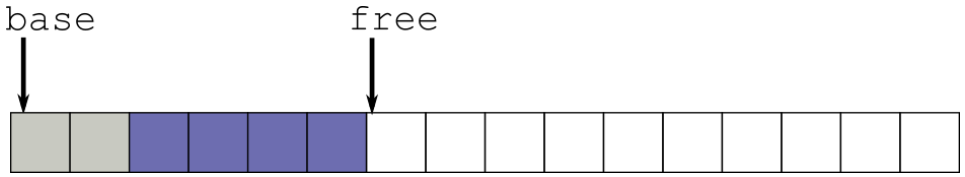
Where is this actually useful?

- Frames in a video game
- Handling of a single event in an event-driven system
- Cyclic execution in a real-time system

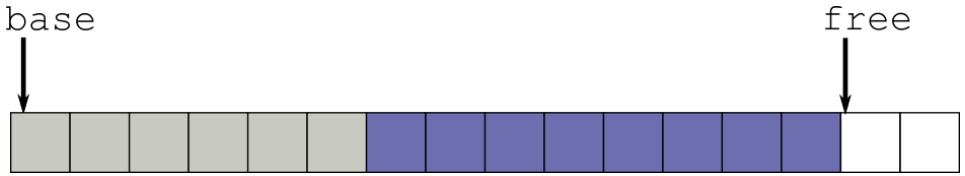
- Containers that are initialized but not changed after
- `static` state - Objects that will never be destroyed

Monotonic Allocator - `std::vector`

Monotonic Allocator - `std::vector`



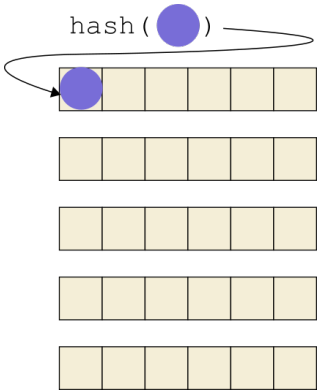
Monotonic Allocator - `std::vector`



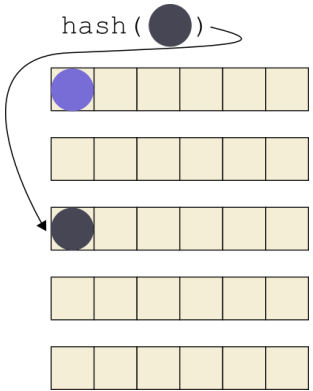
Monotonic Allocator - STL containers

- `vector` should `reserve` final size upfront
- `list` and `map` work fine, but deleted elements are not reclaimed individually
- `deque` works really well
- `unordered_map` has same problem as `vector` when growing but the load-factor triggered rehash is less predictable

unordered_map



unordered_map



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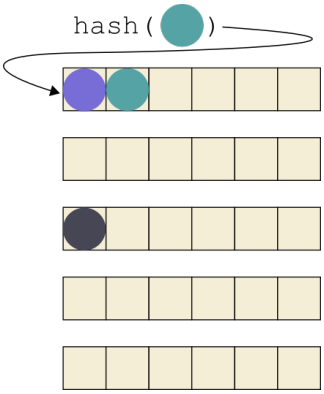
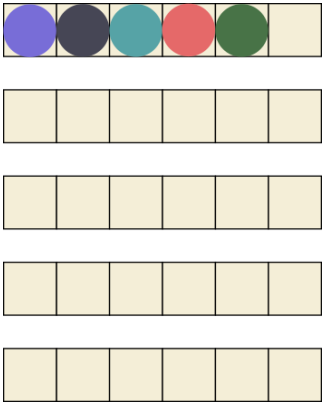
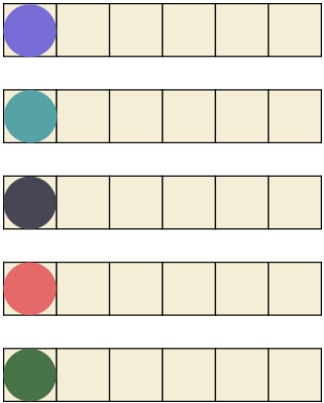


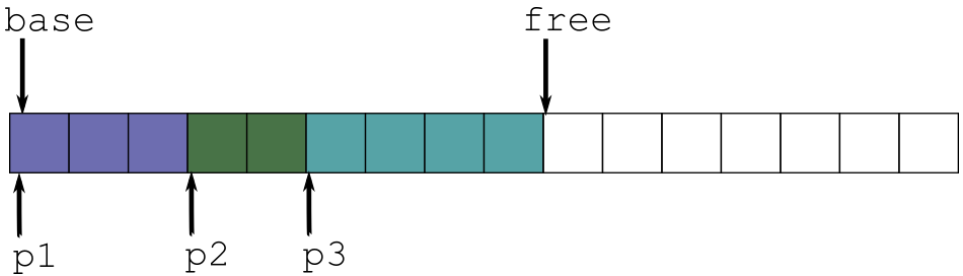
unordered_map





Exact layout depends on hash function and inserted values

Stack Allocator



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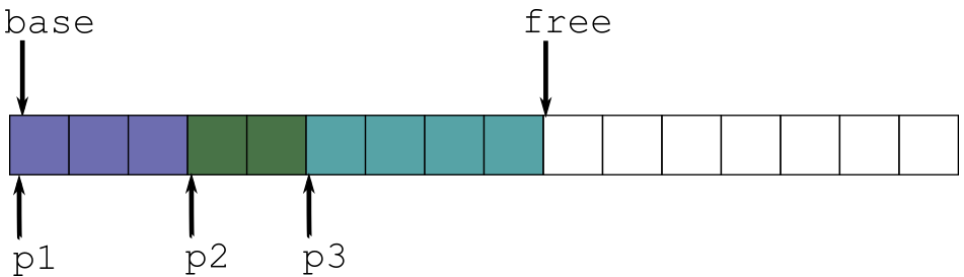
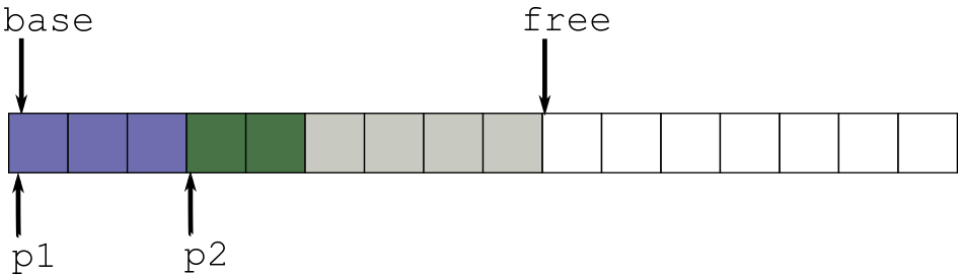



```
monot.deallocate(p3);
```

Stack Allocator

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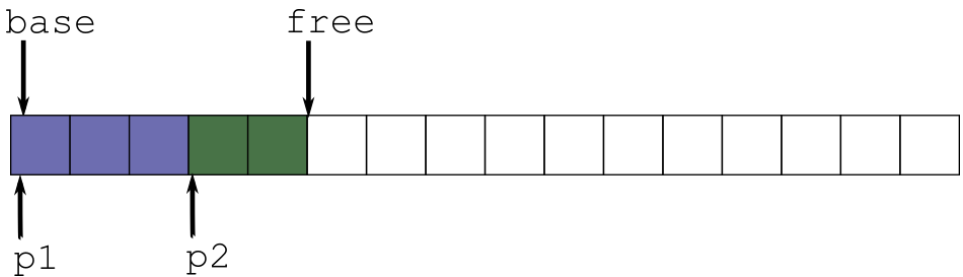
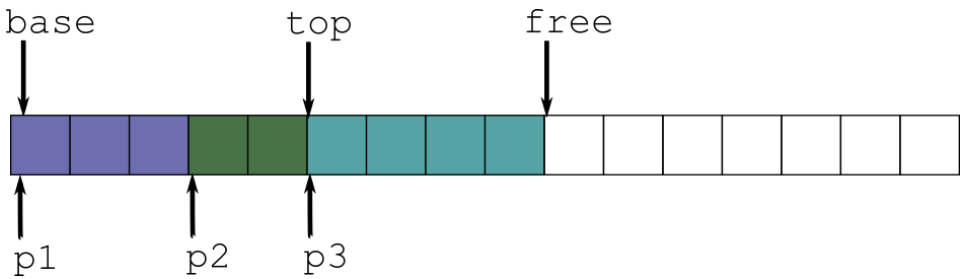



```
monot.deallocate(p3);
```

Stack Allocator

- Strict LIFO-ordering of allocations and deallocations
- No way for the implementation to check whether the deallocation order is correct!

Stack Allocator

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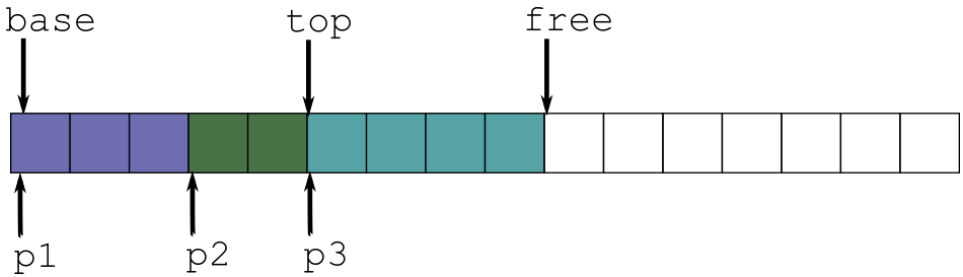
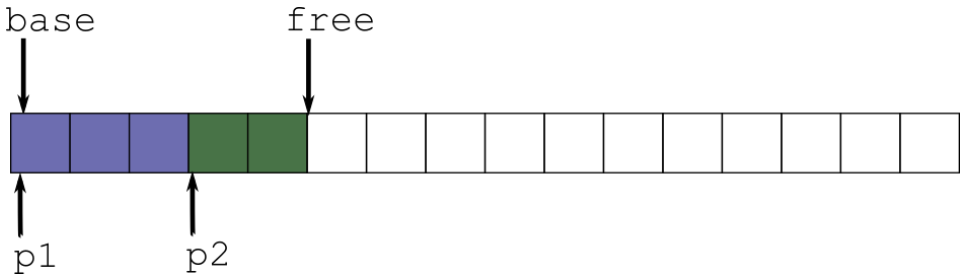


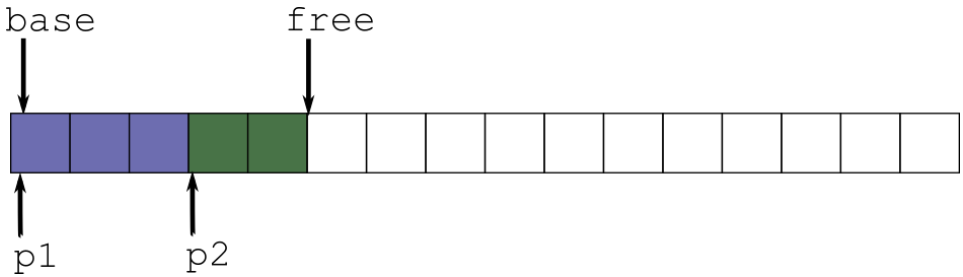

```
monot.deallocate(p3);
```

`p3 == top` ✓

Stack Allocator



Stack Allocator




```
top = ???
```

Stack Allocator

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Stack Allocator

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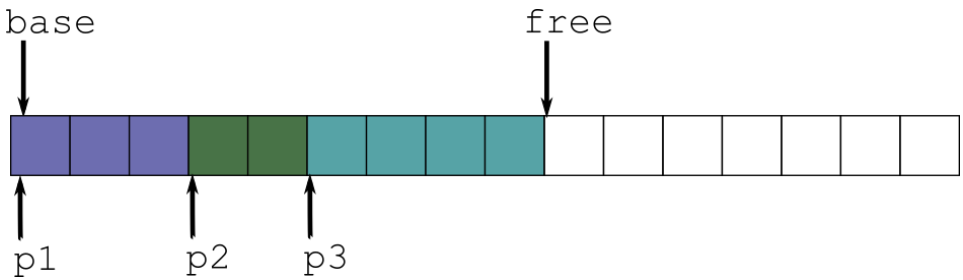
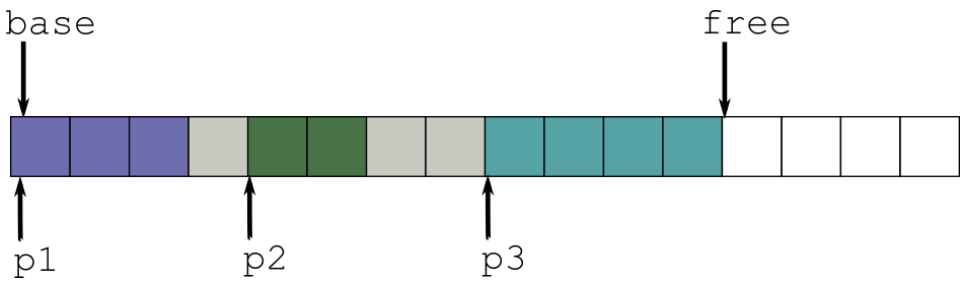
Stack Allocator

- Strict LIFO-ordering of allocations and deallocations.
- No way for the implementation to check whether the deallocation order is correct!
- Free-pointer is reset to the same pointer passed to the `deallocate` call
- Padding bytes may be lost to internal fragmentation

Padding



Padding



Alignment

```
   0xdeadbeef =

  d    e    a    d    b    e    e    f
1101 1110 1010 1101 1011 1110 1110 1111
```

Alignment

```
   0xdeadbeef =

  d    e    a    d    b    e    e    f
1101 1110 1010 1101 1011 1110 1110 1111
```

No alignment (1-byte aligned).

Alignment

```
   0xdeadbeef =

  d    e    a    d    b    e    e    c
1101 1110 1010 1101 1011 1110 1110 1100
```

4-byte aligned.

Alignment

```
   0xdeadbeef =

  d    e    a    d    b    e    e    8
1101 1110 1010 1101 1011 1110 1110 1000
```

8-byte aligned.

Alignment

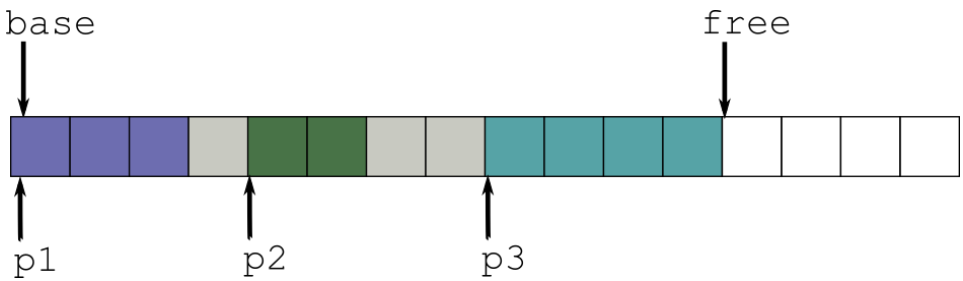
- Alignment refers to the least-significant bits of the object address being 0
- Alignment requirements are always specified in powers of 2
- Each built-in C++ type has a *natural* alignment requirement (typically `alignof(T) == sizeof(T)`)
- This is why `structs` sometimes insert padding bytes between members

Alignment

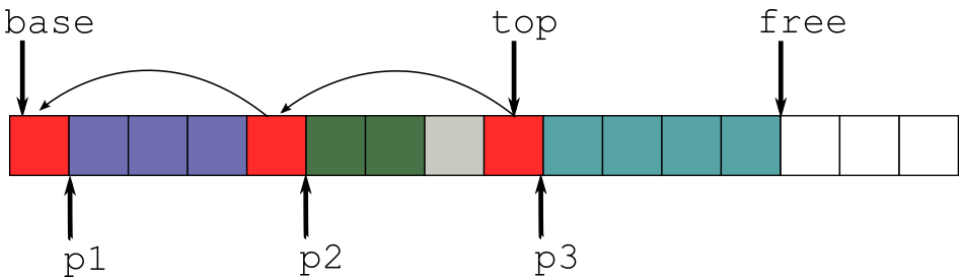
- Default allocator typically returns addresses aligned to `alignof(max_align_t)`, which is big enough for all built-in types
- Users may `extend` the alignment requirement for custom data types using `alignas`

```
void* allocate(std::size_t bytes,
               std::size_t alignment);
```

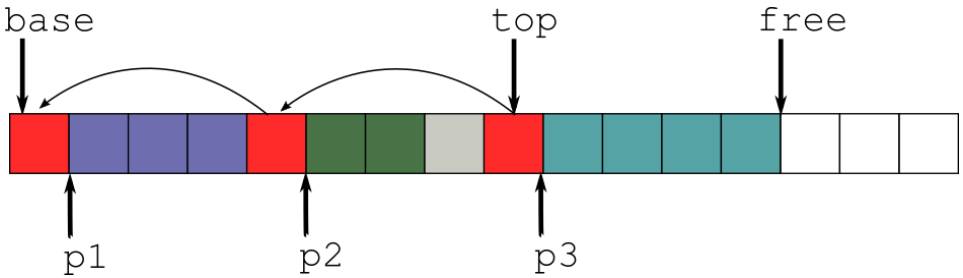
Padding



Monotonic Allocator - Extensions

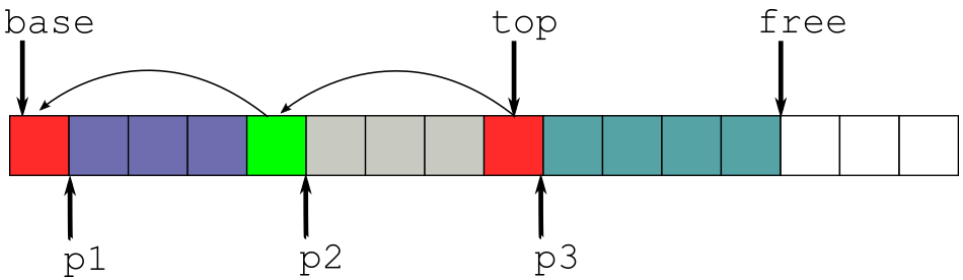


Monotonic Allocator - Extensions




```
extpool.deallocate(p2);
```

Monotonic Allocator - Extensions

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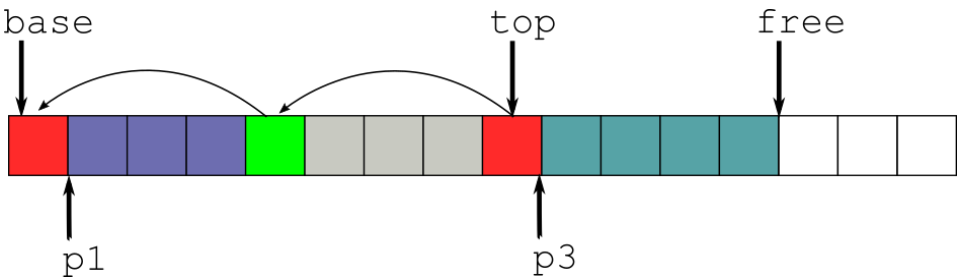
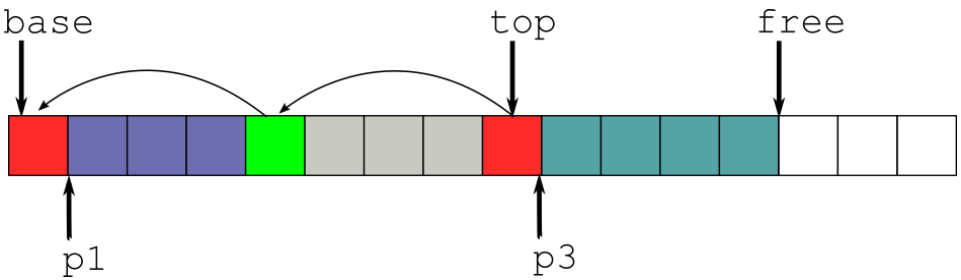
Monotonic Allocator - Extensions



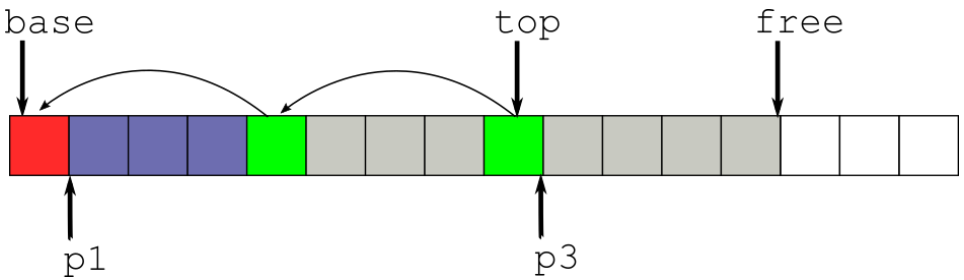

```
extpool.deallocate(p2);
```

Monotonic Allocator - Extensions




```
extpool.deallocate(p2);
extpool.deallocate(p3);
```

Monotonic Allocator - Extensions

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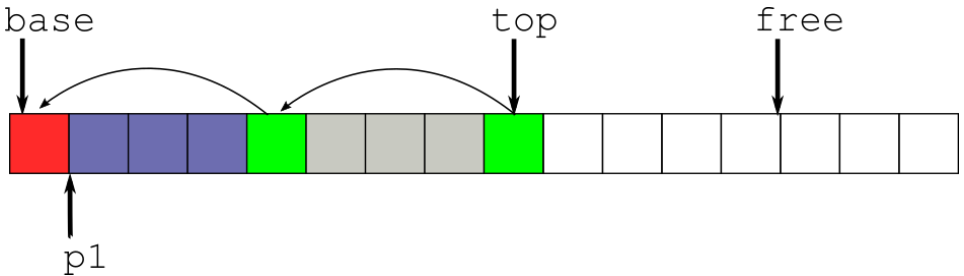
extpool.deallocate(p3);
```

Monotonic Allocator - Extensions




```
extpool.deallocate(p2);
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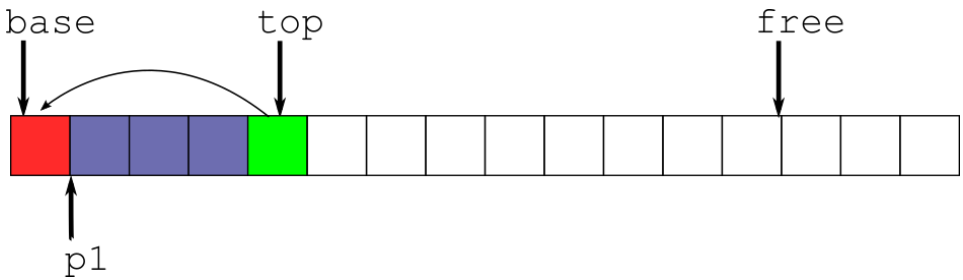
```

Monotonic Allocator - Extensions




```
extpool.deallocate(p2);
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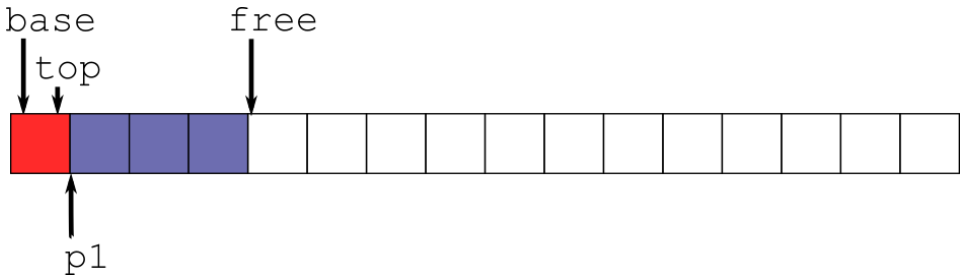
```

Monotonic Allocator - Extensions

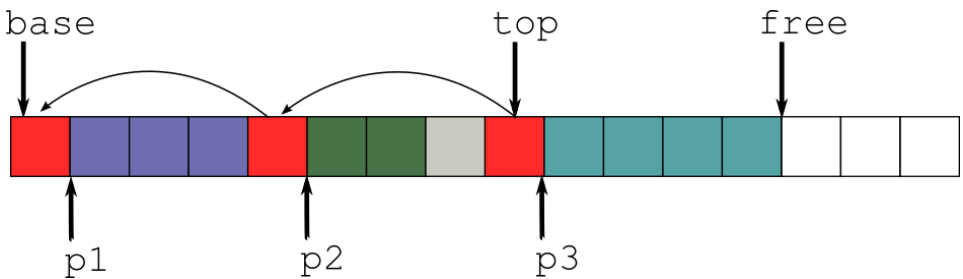



```
extpool.deallocate(p2);
extpool.deallocate(p3);
```

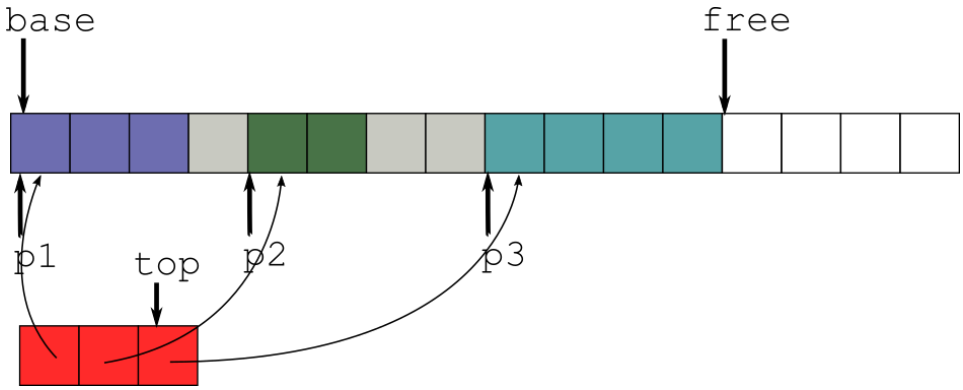
Monotonic Allocator - Extensions

- Auxiliary data structure required
- Runtime cost of deallocation now linear in number of allocations (amortized O(1))
- Auxiliary nodes have their own alignment requirements
- Where to store the auxiliary nodes?

Monotonic Allocator - Extensions



Monotonic Allocator - Extensions



Internal or External?

- External headers have better cache behavior when iterating the list
- External headers might have stricter alignment requirements than data
- Internal headers have better cache behavior when adjacent data is hot
- Internal headers require managed memory to be readable (think GPUs)
- Where does the storage for external headers come from? Same buffer? Different buffer? How big?

$\Rightarrow$ No easy answers.

The Bottom Line...

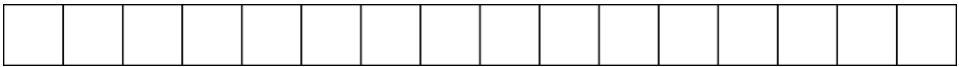
Even seemingly simple extensions get complicated very quickly.

Don't try to increase generality through clever extensions.
Only consider modifications if it's a perfect fit for your use case.

But what if I need to reclaim memory?

$\longrightarrow$ Pool Allocator

Pool Allocator



Pool Allocator

Pool Allocator

```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
auto p3 = pool.allocate(3);
```

Pool Allocator

```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
auto p3 = pool.allocate(3);
```

Pool Allocator

```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
auto p3 = pool.allocate(3);

pool.deallocate(p1);
```

Pool Allocator

```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
auto p3 = pool.allocate(3);

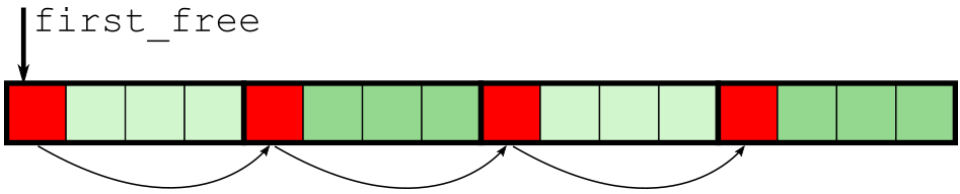
pool.deallocate(p1);
auto p4 = pool.allocate(1);
```

Pool Allocator

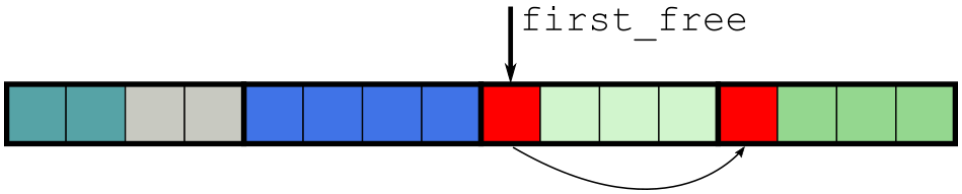
```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
auto p3 = pool.allocate(3);

pool.deallocate(p1);
auto p4 = pool.allocate(1);
```

Pool Allocator - Reclamation

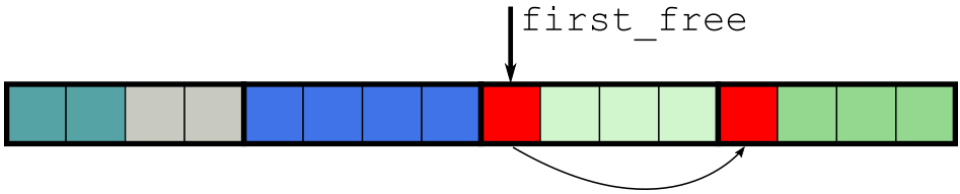


Pool Allocator - Reclamation




```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);
```

Pool Allocator - Reclamation




```
auto p1 = pool.allocate(2);
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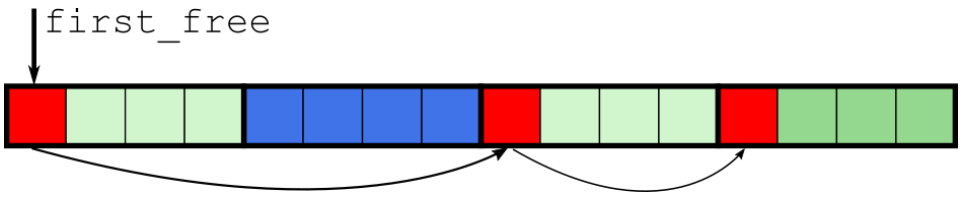
```

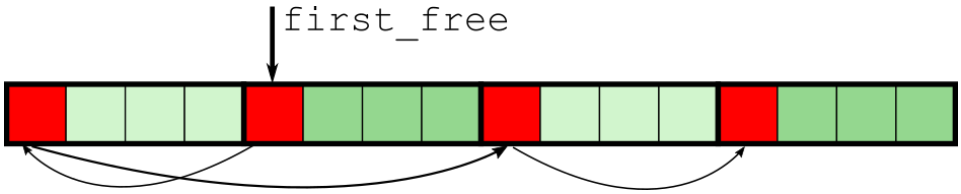
Pool Allocator - Reclamation




```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);

pool.deallocate(p1);
```

Pool Allocator - Reclamation




```
auto p1 = pool.allocate(2);
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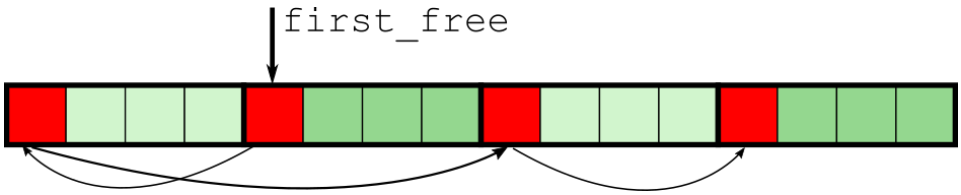
pool.deallocate(p1);
pool.deallocate(p2);
```

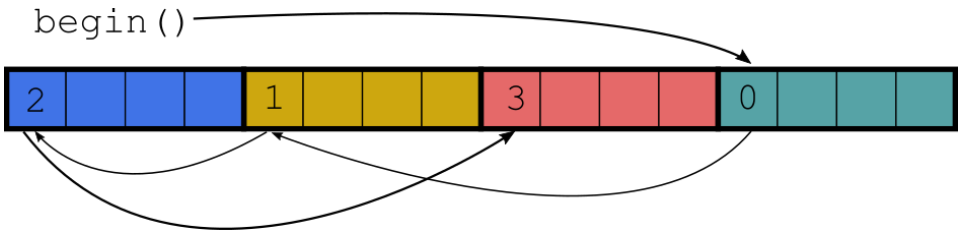
Pool Allocator - Reclamation




```
auto p1 = pool.allocate(2);
auto p2 = pool.allocate(4);

pool.deallocate(p1);
pool.deallocate(p2);
```

Pool Allocator - Diffusion



Pool Allocator

- Deterministic runtime cost
- No external fragmentation
- Easy to make thread-safe

But:

- Cannot serve allocations bigger than chunk size
- High waste through internal fragmentation if sizes of objects vary a lot

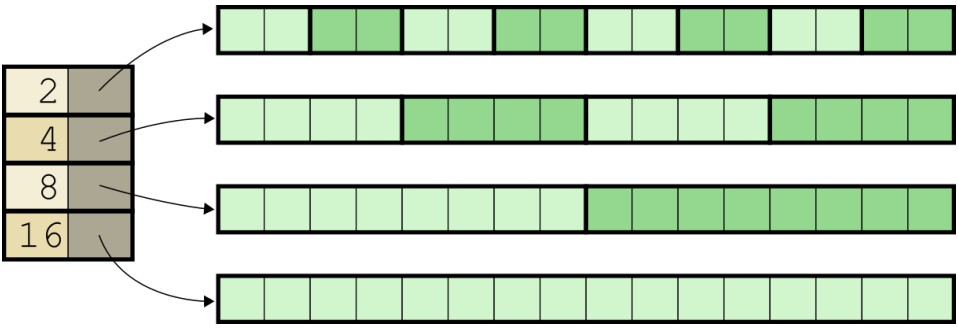
Pool Allocator - STL containers

- `vector` only if chunk sizes match vector size
- `list` and `map` are a perfect fit, as the size of each node is known beforehand (though this knowledge is implementation-specific)
- Similar for `deque`
- `unordered_map` is again complicated

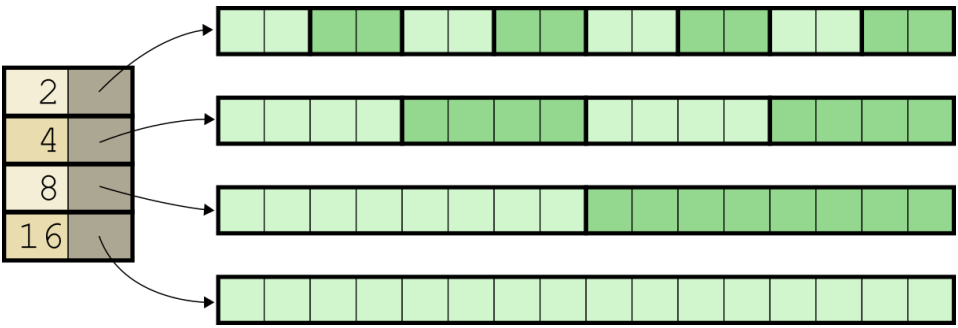
But what if I do need different sizes?

$\longrightarrow$ Multipool Allocator

Multipool Allocator

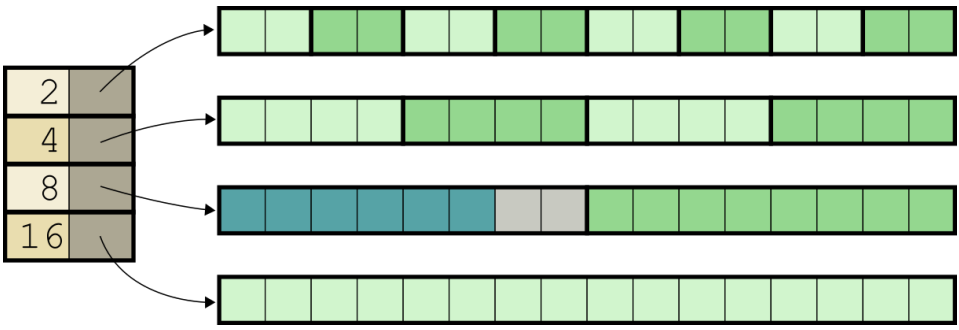


Multipool Allocator




```
auto p1 = multipool.allocate(6);
```

Multipool Allocator

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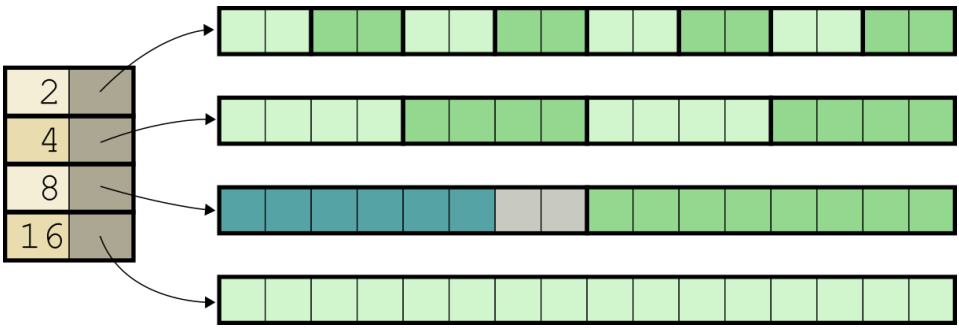
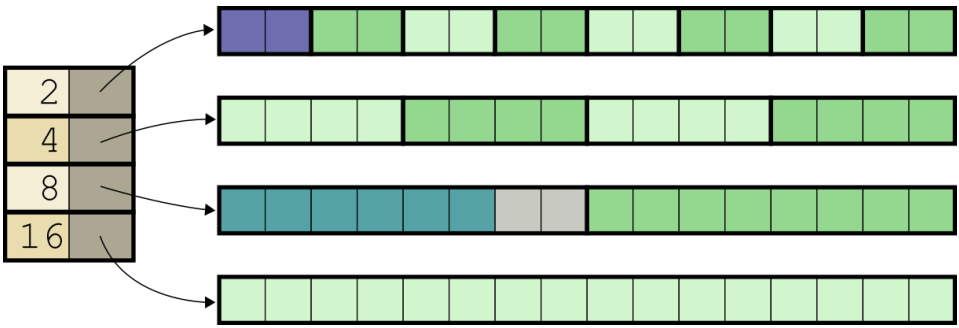
Multipool Allocator




```
auto p1 = multipool.allocate(6);
auto p2 = multipool.allocate(2);
```

Multipool Allocator




```
auto p1 = multipool.allocate(6);
auto p2 = multipool.allocate(2);
```

Multipool Allocator

- Very powerful allocator
- Runtime is still deterministic if number of pools is known beforehand
- Maximum amount of waste through internal fragmentation can be controlled precisely
- Difficult to set up: How many pools do I need? What chunk sizes? What pool sizes?
- Solid building block for a general purpose allocator

Allocator support in C++

```
std::vector<T, Allocator<T>> v;

v.push_back(...);
```

Allocator support in C++

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v.push_back(...);
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This is not the class allocating the memory.

Allocator support in C++

Historically, C++ used Allocators to abstract over different models of addressing memory.
As such, *Allocators* in C++ are "stateless".

[1] Arthur O'Dwyer - An Allocator is a Handle to the Heap

Allocator support in C++

Historically, C++ used Allocators to abstract over different models of addressing memory.
As such, *Allocators* in C++ are "stateless".

In C++ an Allocator is merely a handle to a *memory resource*.[1]

[1] Arthur O'Dwyer - An Allocator is a Handle to the Heap

Allocator support in C++

```
std::pmr::memory_resource& mr = ...;
std::vector<T, std::pmr::polymorphic_allocator> v(&mr);


v.push_back(...);
```

Allocator support in C++

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- Pass a `memory_resource` to handle allocation/deallocation.

Allocator support in C++

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v.push_back(...);
```

- Enable custom allocators for the object.
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C++ Memory Resources[2]

- `std::pmr::memory_resource` - Abstract base class for all resources that can be wrapped in a `std::pmr::polymorphic_allocator`
- `std::pmr::new_delete_resource` - Global allocator
- `std::pmr::monotonic_buffer_resource` - Monotonic allocator
- `std::pmr::unsynchronized_pool_resource`/ `synchronized_pool_resource` - Multipool
- `std::pmr::null_memory_resource` - Allocation always fails

[2]Pablo Halpern - Allocators: The Good Parts

Chaining

```
explicit monotonic_buffer_resource(
  std::pmr::memory_resource* upstream);
```

Each `memory_resource` has an upstream counterpart.

If the resource runs out of memory, it tries to allocate more memory from upstream.

Chaining

Possible uses of Chaining:

- Fixed-size vs. dynamic storage for allocators
- Combination of different allocation strategies
- Injection points for special purpose allocators for debugging and profiling

There's no universal interface for allocators

- Are size and alignment parameters passed to `deallocate`?
- Is `realloc` supported?
- How are out-of-memory errors reported?
- Is extended alignment supported?
- What is the return value for an allocation of size `0`?
- Different memory regions for internal data structures and allocated memory?

Don't underestimate the global allocator

- Competitive performance in the general case
- Security features (ASLR, secure erase of freed memory)
- Debugging & Profiling (Valgrind, Windows Debug Runtime)
- Cache Coloring

Local allocators are no free lunch!

Wrapping up

- No one-size-fits-all — Each allocator has its Achilles heel
- Global allocator is a good solution for the general case
- But you can do better with special allocators for special use cases, in terms of performance[3] as well as reliability
- C++ has good support for local allocators, but the terminology is a bit off
- Different libraries have different concepts of allocators
- No free lunch: You need to understand your use case before you can chose the right allocator

[3] John Lakos - Local (Arena) Allocators

Thanks for your attention.